Aquatic Solutions Conference Agenda

7:30 a.m. Breakfast 9:00 a.m Welcome Opening Comments 9:15 a.m. Why be tethered to old conventions of underwater exploration? by: Durval Tavares 10:00 a.m. Coral reef mapping using low cost Remotely Operated Vehicle by: Kirk Bennett 10:30 a.m. *Networking Break* 11:00 a.m. Inspection Class ROVs: The pickup trucks of the subsea industry by: Chris Parker 11:30 a.m. Survey of thruster design principals for underwater robots by: Sheldon Rubin 12:00 p.m. *Lunch* 1:00 p.m. Lessons learned from the preparation of off-the-shelf electronic components for the pressure-tolerant usage in deep-sea by: Peter Kampmann 1:30 p.m. Optimizing seaglider performance utilizing a annular wing by: Christopher Hockley 2:00 p.m. Networking Break 2:30 p.m. Underwater solutions with "out of the box" components by: Carsten Horn 3:00 p.m. Hydrocarbon detection with vertical E-field measurements on the seafloor by: Stefan Helwig 3:30 p.m. Closing Remarks

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